

MG Master LV

- Communication guide -

MG Master LV 24-48V / 72-96V



MG Energy Systems B.V.



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1 GENERAL

This communication guide will give insight on the data that is transmitted by the Master LV according to the selected protocol. Required Master LV firmware version is 1.36 or higher.

1.1 Document history

Table 1 - Document history

| Rev | Date | Revision author |
|------|--|-----------------|
| 1.36 | 2024-02-07 | W. Portinga |
| | Modifications: <ul style="list-style-type: none"> Changed MG REGS Periodically/on change settings, see 3.5.2 | |
| 1.35 | 2023-07-14 | W. Portinga |
| | Modifications: <ul style="list-style-type: none"> Added bit 29 to System Status external 1, see 3.5.2 Added bit 27 to System warning external 1, see 3.5.2 Added bit 6 to System warning external 2, see 3.5.2 Added bit 20 and 21 to System failure external 1, see 3.5.2 | |
| 1.34 | 2023-06-14 | W. Portinga |
| | Modifications: <ul style="list-style-type: none"> Typo fix, kelvin data type from “int16” to “uint16”, see 3.3.3 Added warning flag to System warning external 2 bit 5, see 3.5.2 Relocated “Output voltage” from MGREG 3.5 to VREG 3.4 Typo fix, battery voltage data type from Battery basic info, “uint16” to “int16”, see 4.2 and 5.2 | |
| 1.32 | 2023-01-10 | W. Portinga |
| | Modifications: <ul style="list-style-type: none"> Updated status flags VREG 0x2100, see 3.4.2 “Status flags”. Updated BMS error values VREG 0x2101, see 3.4.2 “BMS error”. Added PGN information, see 3.3.1 and 3.3.2. | |
| 1.31 | 2022-10-05 | W. Portinga |
| | Modifications: <ul style="list-style-type: none"> Added MG NMEA2000 Protocol Removed deprecated VE NMEA2000 Protocol. Added system voltage, status, warning and failure MG registers to 3.5.2 | |
| 8 | 2020-09-07 | W. Portinga |
| | Modifications: <ul style="list-style-type: none"> Added General BMS protocol, see 5 “General BMS protocol”. | |
| 7 | 2020-07-01 | W. Portinga |
| | Modifications: <ul style="list-style-type: none"> Typo, name of “DC discharge voltage” and “DC discharge current limitation” swapped, see 3.4.2 “BMS Limits”. Added status flags VREG 0x2100, bit 13 and 14, see 3.4.2 “Status flags”. Added BMS error value VREG 0x2101, value 18, see 3.4.2 “BMS error”. Added setting Bluetooth enable VREG 0x0090, see 3.4.2 “Bluetooth enable”. Typo, removed “(not implemented yet)” from VREG’s Battery charge voltage, DC charge current limitation, Battery discharge voltage, DC discharge current limitation, see 3.4.2. | |



2 COMMUNICATION WITH THE MG MASTER LV

Communication with the MG Master LV can be established via CAN-Bus. In this document there are 3 protocols that are described:

- MG NMEA2000 PROTOCOL;
- SMA PROTOCOL;
- GENERAL BMS PROTOCOL;

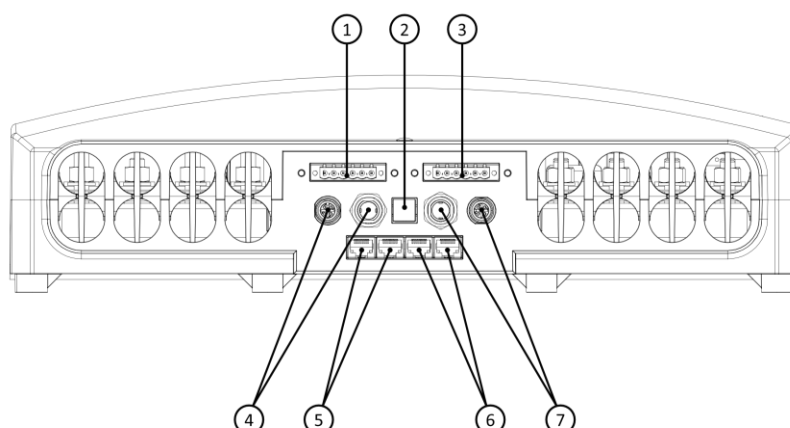
Other protocol's that are available on the Master LV are deprecated and no longer supported for new systems designs.

Note:

- Only one protocol can be selected, a combination of SMA with NMEA2000 is not possible.
- General BMS protocol is the SMA protocol with added messages not supported by SMA.

2.1 CAN Interface

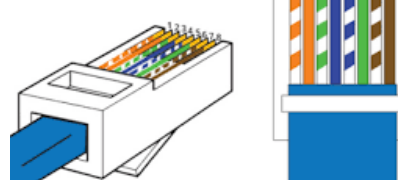
The CAN interface on Master LV is available in two different physical connectors: RJ45 and M12. The location at the Master LV are the two most right side connectors, see image below, number 6 and 7.



2.1.1 RJ45 Connector details

Typical cables that are used for the RJ45 CAN-Bus connections are standard CAT 5 Ethernet network patch cables.


Table 2 – RJ45 connector details

| Pin | Description | Connector view |
|-----|-------------|---|
| 1 | | <div style="text-align: center;"> RJ45 Pinout T-568B </div>  |
| 2 | | |
| 3 | GND | |
| 4 | | |
| 5 | | |
| 6 | V+ | |
| 7 | CAN-H | |
| 8 | CAN-L | |

2.1.2 M12 Connector details

The connectors used for connecting the CAN-bus are all of the same type, namely a circular M12 connector with 5 positions and A-coded keying.

Table 3 – Circular M12 connector with 5 positions A-coded details

| Pin | Description | Connector view |
|-----|-------------|---|
| 1 | Shield | <p>M12, 5-pin, A-coded</p>  <p>Male Female</p> |
| 2 | V+ | |
| 3 | GND | |
| 4 | CAN-H | |
| 5 | CAN-L | |
| | | |

Cables to be used for the battery system are typically referred to as NMEA 2000 or DeviceNet compatible cables. The minimum requirements for cables are:

- Twisted pair connected to pins 4 and 5 for communication with a minimum wire cross sectional area of 0.2 mm² (24 AWG).
- Pair of conductors connected to pin 2 and 3 for power and HVIL with a minimum wire cross sectional area of 0.34 mm² (22 AWG).
- Cable with braided shielding connected to pin 1.



NOTICE:

Do not use sensor/actor cables. They often don't have any twisted pairs and are therefore not suitable for this application.

3 MG NMEA2000 PROTOCOL

There are 3 NMEA2000 protocol options. The MG-NMEA2000 protocol is using a NMEA2000 manufacturer code assigned for “MG energy systems”, recommended for new designs. The VE-NMEA2000 protocols are using a NMEA2000 manufacturer code assigned for “Victron Energy”.



NOTICE:

When Micropower chargers are enabled in the settings, 11-bit CAN messages with ID 0x600 will be added on the NMEA2000 bus. These messages are not explained in this document.

3.1 Interface definition

Speed : 250 kbps
ID : 29-bit CAN 2.0B

3.2 Message definition

NMEA2000 Identifier definition.

<3-bits priority><1-bit reserved><1-bit datapage>< 16-bits PGN >< 8-bit source address >

As described in the list below a PGN consists of datapage + PGN. For example 0x1F214 means:

Datapage = 1

PGN = 0XF214

3.3 PGN list

Table 4 - PGN list

| Data | PGN Name | PGN dec | PGN hex | Field | Remarks |
|----------------------------------|---------------------|---------|---------|-------|--------------------|
| | ISO Address Claim | 060928 | 0xEE00 | | |
| | Product information | 126996 | 0x1F014 | | |
| Battery pack voltage | Battery Status | 127508 | 0x1F214 | 2 | Battery instance 0 |
| Battery pack current | Battery Status | 127508 | 0x1F214 | 3 | Battery instance 0 |
| Battery pack highest temperature | Battery Status | 127508 | 0x1F214 | 4 | Battery instance 0 |
| State-Of-Charge (SOC) | DC detailed status | 127506 | 0x1F212 | 4 | DC instance 0 |
| Time-To-Go (TTG) | DC detailed status | 127506 | 0x1F212 | 6 | DC instance 0 |
| Lowest cell voltage in pack | Battery Status | 127508 | 0x1F214 | 2 | Battery instance 1 |
| Lowest cell temperature in pack | Battery Status | 127508 | 0x1F214 | 4 | Battery instance 1 |
| Highest cell voltage in pack | Battery Status | 127508 | 0x1F214 | 2 | Battery instance 2 |
| Highest cell temperature in pack | Battery Status | 127508 | 0x1F214 | 4 | Battery instance 2 |

Notes:

- Battery instance 0 and DC Instance 0 are the same;
- One or more MG Lithium-Ion batteries together in one system are a Battery pack;
- The DC detailed status is a NMEA2000 fast packet;
- The default source address of the MG Master HV is 0x50;
- PGN name BATTERY_BANK is also named BATTERY_STATUS.

The Data instance from PGN: 127508 BATTERY_BANK or PGN: 127506 DC_DETAILED can be changed by steps of 32 -> 0, 32, 64, 96, 128. If data instance from BATTERY_BANK is changed, also data instance of DC_DETAILED will change, vice versa. Data instance from BATTERY_BANK_MIN, BATTERY_BANK_MAX are increased with the data instance from BATTERY_BANK.

Table 5 - Data instance from PGN's

| BATTERY_BANK DC_DETAILED | BATTERY_BANK_MIN | BATTERY_BANK_MAX |
|-----------------------------|------------------|------------------|
| 0 | 1 | 2 |
| 32 | 33 | 34 |
| 64 | 65 | 66 |
| ... | ... | ... |
| 224 | 225 | 226 |

- Data instance is stored, if during boot data instance is invalid, it will be restored to 0.
- DeviceInstance can be changed and is stored.
- DeviceFunctionInstance can be changed and is stored.
- Device Class Instance can be changed and is stored.

3.3.1 PGN: ISO Address Claim, 060928 (0xEE00)

NMEA2000 manufacturer code for MG Energy Systems B.V. is 1160

Unique Number (ISO Identity Number): unique number subtracted from serial number.

Manufacturer Code (industry marine + manufacturer code): 0x9C88

Device Instance Lower (ISO ECU Instance): 0

Device Instance Upper (ISO Function Instance): 0

Device Function (ISO Function): 170

Device Class: 35

System Instance (ISO Device Class Instance): 0 ->(ISO Function Instance)

Industry Group: 4 (Marine)

NMEA Reserved (ISO Self Configurable): 1

3.3.2 PGN: Product information, 126996 (0x1F014)

NMEA Network Message Database Version: 1301

NMEA Manufacturer's Product Code: 0xFFFF

Manufacturer's Model ID: String containing device name, example MG BMS 24-48V/600A

Manufacturer's Software Version Code: String containing software version

Manufacturer's Model Version: String containing hardware version

Manufacturer's Model Serial Code: MGE(SerialNumber)

NMEA 2000 Certification Level: 1

Load Equivalency: 1

3.3.3 PGN: Battery Status, 127508 (0x1F214)

There are three battery status messages that are separated by the "Battery Instance".

3.3.3.1 Battery Instance "0"

| 0x1F214 - Battery Status | | | |
|--------------------------|------------------|---|-----------------------------|
| Periodicity: | | 1500 milliseconds | |
| Priority Default: | | 6 | |
| Format: | | Little Endian/Intel convention | |
| Single Frame: | | Yes | |
| 1 | Byte 0 | Battery Instance = 0. | |
| | | Data Length: | 8 bit, uint8 |
| | | Unit: | Generic numeric ID, short |
| | | Resolution: | 1 bit |
| | | Range: | 0 to 252 |
| 2 | Byte 1 Byte 2 | Battery Voltage DC. | |
| | | Data Length: | 16 bit, int16 |
| | | Unit: | Voltage, DC |
| | | Resolution: | 0.01 V |
| | | Range: | +/- 327.64 V |
| 3 | Byte 3 Byte 4 | Battery Current, + = battery is charged, - = battery is discharged. | |
| | | Data Length: | 16 bit, int16 |
| | | Unit: | Current, Electric |
| | | Resolution: | 0.1 A |
| | | Range: | +/- 3276.4 A |
| 4 | Byte 5 Byte 6 | Highest Battery Temperature | |
| | | Data Length: | 16 bit, uint16 |
| | | Unit: | Generic Temperature, Kelvin |
| | | Resolution: | 0.01 K |
| | | Range: | 0 to 655.32 deg K |
| 5 | Byte 7 | Sequence ID, an upward counting number used to tie related information together between different PGNS. | |
| | | Data Length: | 8 bit, uint8 |
| | | Unit: | Sequence ID, short |
| | | Resolution: | 1 bit |
| | | Range: | 0 to 252 |

3.3.3.2 Battery Instance "1"

| 0x1F214 - Battery Status Lowest Value's | | | |
|---|------------------|--------------------------------|---------------------------|
| Periodicity: | | 1500 milliseconds | |
| Priority Default: | | 6 | |
| Format: | | Little Endian/Intel convention | |
| Single Frame: | | Yes | |
| 1 | Byte 0 | Battery Instance = 1. | |
| | | Data Length: | 8 bit, uint8 |
| | | Unit: | Generic numeric ID, short |
| | | Resolution: | 1 bit |
| | | Range: | 0 to 252 |
| 2 | Byte 1 Byte 2 | Lowest cell voltage in pack | |
| | | Data Length: | 16 bit, int16 |
| | | Unit: | Voltage, DC |

| | | | |
|---|------------------|---|-----------------------------|
| | | Resolution: | 0.01 V |
| | | Range: | +/- 327.64 V |
| 3 | Byte 3 Byte 4 | not implemented (0x7FFF) | |
| | | Data Length: | 16 bit, int16 |
| | | Unit: | - |
| | | Resolution: | - |
| | | Range: | - |
| 4 | Byte 5 Byte 6 | Lowest cell temperature in pack | |
| | | Data Length: | 16 bit, uint16 |
| | | Unit: | Generic Temperature, Kelvin |
| | | Resolution: | 0.01 K |
| | | Range: | 0 to 655.32 deg K |
| 5 | Byte 7 | Sequence ID, an upward counting number used to tie related information together between different PGNs. | |
| | | Data Length: | 8 bit, uint8 |
| | | Unit: | Sequence ID, short |
| | | Resolution: | 1 bit |
| | | Range: | 0 to 252 |

3.3.3.3 Battery Instance "2"

| 0x1F214 - Battery Status Highest Value's | | | |
|--|------------------|---|-----------------------------|
| Periodicity: | | 1500 milliseconds | |
| Priority Default: | | 6 | |
| Format: | | Little Endian/Intel convention | |
| Single Frame: | | Yes | |
| 1 | Byte 0 | Battery Instance = 2. | |
| | | Data Length: | 8 bit, uint8 |
| | | Unit: | Generic numeric ID, short |
| | | Resolution: | 1 bit |
| | | Range: | 0 to 252 |
| 2 | Byte 1 Byte 2 | Highest cell voltage in pack | |
| | | Data Length: | 16 bit, int16 |
| | | Unit: | Voltage, DC |
| | | Resolution: | 0.01 V |
| | | Range: | +/- 327.64 V |
| 3 | Byte 3 Byte 4 | not implemented (0x7FFF) | |
| | | Data Length: | 16 bit, int16 |
| | | Unit: | - |
| | | Resolution: | - |
| | | Range: | - |
| 4 | Byte 5 Byte 6 | Highest cell temperature in pack | |
| | | Data Length: | 16 bit, uint16 |
| | | Unit: | Generic Temperature, Kelvin |
| | | Resolution: | 0.01 K |
| | | Range: | 0 to 655.32 deg K |
| 5 | Byte 7 | Sequence ID, an upward counting number used to tie related information together between different PGNs. | |
| | | Data Length: | 8 bit, uint8 |
| | | Unit: | Sequence ID, short |

| | | | |
|--|--|-------------|----------|
| | | Resolution: | 1 bit |
| | | Range: | 0 to 252 |

3.3.4 PGN: DC Detailed Status, 127506 (0x1F212)

| 0x1F212 -DC Detailed Status | | | |
|-----------------------------|------------------|---|------------------------------------|
| Periodicity: | | 1500 milliseconds | |
| Priority Default: | | 6 | |
| Format: | | Little Endian/Intel convention | |
| Single Frame: | | No (fast packet) | |
| 1 | Byte 0 | Sequence ID, an upward counting number used to tie related information together between different PGNs. | |
| | | Data Length: | 8 bit, uint8 |
| | | Unit: | Sequence ID, short |
| | | Resolution: | 1 bit |
| | | Range: | 0 to 252 |
| 2 | Byte 1 | DC Instance. | |
| | | Data Length: | 8 bit, uint8 |
| | | Unit: | Generic numeric ID, short |
| | | Resolution: | 1 bit |
| | | Range: | 0 to 252 |
| 3 | Byte 2 | DC Type | |
| | | Data Length: | 8 bit, int8 |
| | | Unit: | - |
| | | Resolution: | 1 bit |
| | | Range: | Variable |
| | | 0x00 = Battery, 0x01 = Alternator, 0x02 = Convertor, 0x03 = Solar Cell, 0x04 = Wind Generator, 0x05 ... 0xFD = Reserved, 0xFE = Error, 0xFF = Data Not Available | |
| 4 | Byte 3 | State-Of-Charge | |
| | | Data Length: | 8 bit, uint8 |
| | | Unit: | Generic Absolute Percentage 0-252% |
| | | Resolution: | 1 % |
| | | Range: | 0 to 252 % |
| 5 | Byte 4 | State-Of-Health | |
| | | Data Length: | 8 bit, uint8 |
| | | Unit: | Generic Absolute Percentage 0-252% |
| | | Resolution: | 1 % |
| | | Range: | 0 to 252 % |
| 6 | Byte 5 Byte 6 | Time remaining | |
| | | Data Length: | 16 bit, uint16 |
| | | Unit: | Time |
| | | Resolution: | 1 minute |
| | | Range: | 0 to 65532 minutes |

| | | | |
|---|-------------------|----------------------------------|-------------------|
| 7 | Byte 7 Byte 8 | Ripple voltage (not implemented) | |
| | | Data Length: | 16 bit, uint16 |
| | | Unit: | AC ripple voltage |
| | | Resolution: | 1 mV |
| | | Range: | 0 to 65532 mV |
| 8 | Byte 9 Byte 10 | Amp hours | |
| | | Data Length: | 16 bit, uint16 |
| | | Unit: | Battery capacity |
| | | Resolution: | 1 Ah |
| | | Range: | 0 to 65532 Ah |

The DC detailed status is actually two messages that are combined as one.

NOTE: The DC detailed message is a NMEA2000 fast packet. This means that it has a little protocol overhead.

The message consists out of 2 messages.

Table 6 - DC detailed fast packet

| Message | Byte 0 | Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 | Byte 6 | Byte 7 |
|---------|--|---|--------|----------------|------------------------|------------------------|----------------|-----------------------------|
| 1 | b0 to b4 = 00000 b4 to b7 = 3-bit Sequence counter | Total number of data bytes. For this PGN it is 0x0B. | SID | DC Instance | DC type | SOC | SOH (=0xFF) | Time remaining byte 0 |
| 2 | b0 to b4 = frame counter b4 to b7 = 3-bit Sequence counter | Time remaining byte 1 | 0xFF | 0xFF | Amp hours byte 0 | Amp hours byte 1 | 0xFF | 0xFF |

= DC Detailed Status PGN

3.4 Victron VREGS

3.4.1 Message definition

CAN-ID : 1CEF <target address><source address>

Example : 1CEF5030 means source address 0x30 end target address 0x50

0xFF as target address means broadcast message. Every node will receive this message.

All fields are sent in Little Endian order. Message data of a VREG looks like the following:

Table 7 - VREG message data

| Byte 0 | Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 | Byte 6 | Byte 7 |
|--------|--------|---------|---------|--------|--------|--------|--------|
| 0x66 | 0x99 | regId.L | regId.H | Data | Data | Data | Data |

3.4.2 VREG ID List

If “periodically” is “Yes” the VREG is broadcasted with an interval of 5 seconds. If “on change” is “yes” the VREG will be broadcasted directly if the value has been changed. The “on change” condition can have a maximum delay of 1 second.

| Description | VREG ID | Period-ically/on Change | Comments |
|--------------------------|---------|-------------------------|--|
| Device | | | |
| Product ID | 0x0100 | No/No | Lynx Ion BMS General = 0xA390 Lynx Ion BMS 150A = 0xA391 Lynx Ion BMS 400A = 0xA392 Lynx Ion BMS 600A = 0xA393 Lynx Ion BMS 1000A = 0xA394 MG BMS 24-96V General = 0xB0C0 MG BMS 24-48V/150A = 0xB0C1 MG BMS 24-48V/400A = 0xB0C2 MG BMS 24-48V/600A = 0xB0C3 MG BMS 24-48V/1000A = 0xB0C4 MG BMS 72V/400A = 0xB0C5 MG BMS 96V/600A = 0xB0C6 MG BMS 72-96V/500A = 0xB0C7 |
| Firmware version | 0x0102 | No/No | un8 = Identifier : un24 = Firmware Version, 0xFFFFFF = no firmware present, Firmware version: 0x123456=v12.34.56 |
| Serial number | 0x010A | No/No | stringZeroEnded[32] = Serial : un8 = padding, 0 = zero padding (not implemented) |
| Model name | 0x010B | No/No | stringZeroEnded[64] = Model : un8 = padding, 0 = zero padding (not implemented) |
| BMS Status values | | | |
| Voltage | 0xED8D | Yes/No | sn16 = DC Channel 1 Voltage [0.01V], 0x7FFF = Not Available |
| Current | 0xED8F | Yes/No | sn16 = DC Channel 1 Current [0.1A], 0x7FFF = Not Available |
| Cell Volt. max/min | 0x0385 | Yes/No | un16 = Minimum voltage [0.01V] : un16 = Maximumvoltage [0.01V] |

| Description | VREG ID | Period-ically/on Change | Comments |
|--------------------------|---------|-------------------------|--|
| Cell Temperature max/min | 0x0386 | Yes/No | un16 = Minimum temperature [0.01K] : un16 =Maximum temperature [0.01K] |
| State-of-Charge | 0x0FFF | Yes/Yes | un16 = SOC [0.01%] |
| Time-to-go | 0x0FFE | No/No | un16 = Time to go [1minutes], 0xFFFF = not available |
| Consumed Ah | 0xEEFF | No/No | sn32 = Consumed Ah [0.1Ah] |
| Last error 1-4 | 0x2110 | No/Yes | un8 = Error 1, Last error : un8 = Error 2 : un8 = Error 3 : un8 = Error 4, Oldest error |
| Last error 1 time | 0x2111 | No/Yes | un32 = BMS: UTC time of last error 1 |
| Last error 2 time | 0x2112 | No/Yes | un32 = BMS: UTC time of last error 2 |
| Last error 3 time | 0x2113 | No/Yes | un32 = BMS: UTC time of last error 3 |
| Last error 4 time | 0x2114 | No/Yes | un32 = BMS: UTC time of last error 4 |
| Status flags | 0x2100 | No/Yes | un32 = BMS page BMV flags (bit flags) bit 0 = Charged bit 1 = Almost charged bit 2 = Discharged bit 3 = Almost discharged bit 4 = Charging bit 5 = Discharging bit 6 = Balancing in progress bit 7 = Main safety contactor closed bit 8 = Main safety contactor closed bit 9 = Alarm over voltage bit 10 = Warning over voltage bit 11 = Alarm under voltage bit 12 = Warning under voltage bit 13 = Warning high charge current bit 14 = Warning high discharge current bit 15 = Alarm over temperature bit 16 = Warning over temperature bit 17 = Warning under temperature charge bit 18 = Alarm under temperature charge bit 19 = Warning under temperature discharge bit 20 = Alarm under temperature discharge bit 21 = Low SOC (< 20%) bit 22 = Alarm under temperature bit 23 = Alarm short circuit (not implemented) bit 24 = Alarm hardware failure bit 25 = Allowed to charge bit 26 = Allowed to discharge bit 27 = Pre-alarm (not implemented) bit 28 = Warning bad contactor (not implemented) |

| Description | VREG ID | Period-ically/on Change | Comments |
|-----------------------------|---------|-------------------------|---|
| | | | bit 29 = Alarm high current bit 30 = Warning cell imbalance bit 31 = Warning service requested |
| BMS State | 0x0371 | No/Yes | un8 =BMS state (Value) 0-8= Initializing 9 = Running 10= Error 12 = Shutting down 13 = Updating battery firmware 14 = Standby 15 = Going to running state 16 = Pre-charging |
| BMS Error | 0x2101 | No/Yes | un8 = BMS error (Value) 0 = No error, system OK 2 = No batteries found 4 = Batteries connected are not the same type 5 = Number of batteries connected incorrect 7 = Measure error 11 = Hardware failure 12 = Watchdog error 13 = Over voltage detected 14 = Under voltage detected 15 = Over temperature detected 16 = Under temperature detected 18 = Battery protection automatic shutdown 23 = BMS slave failure 25 = Pre-charge failure 26 = Contactor failure 27 = Over current 28 = Slave update failure 29 = Slave update unavailable 35 = Pre-charge timeout 37 = Interlock 38 = Emergency stop 39 = Communication timeout 41 = Terminal over temperature |
| Programmable relay state | 0x034E | No/Yes | un8 = programmable relay state, 0 = open, 1 = closed. |
| System configuration | | | |
| Battery installed capacity | 0x1000 | No/Yes | un16 = Battery capacity [Ah] |

| Description | VREG ID | Period-ically/on Change | Comments |
|--------------------------------------|--------------------------------------|-------------------------|---|
| Battery installed configuration | 0x0380 | No/Yes | un8 = Number of batteries : un8 = Cells per battery : un8= Number of batteries in parallel : un8 =Number of batteries in series |
| | | | |
| History values | | | |
| Deepest discharge | 0x0300 | No/No | sn32 = Deepest discharge [0.1Ah] |
| Total Ah drawn | 0x0305 | No/No | sn32 = Cumulative Ah drawn from the battery [0.1Ah] |
| Minimum voltage | 0x0306 | No/No | sn32 = Minimum battery voltage [0.01V] |
| Maximum voltage | 0x0307 | No/No | sn32 = Maximum battery voltage [0.01V] |
| Automatic syncs | 0x0309 | No/No | sn32 = Number of automatic synchronizations |
| Discharged energy | 0x0310 | No/No | un32 = The amount of energy drawn from the source [0.01kWh] |
| Charged energy | 0x0311 | No/No | un32 = The amount of energy put into the source [0.01kWh] |
| Maximum temperature | 0x0312 | No/No | un16 = The maximum temperature [0.01K] |
| Minimum temperature | 0x0313 | No/No | un16 = The minimum temperature [0.01K] |
| Min/Max cell voltage | 0x0384 | No/No | un16 = Minimum voltage [0.01V] : un16 = Maximum voltage [0.01V] |
| | | | |
| BMS Limits | | | |
| Battery charge voltage | 0x0390 | Yes/Yes | un32 = Charge voltage [0.01V], 0xFFFFFFFF = Not Available |
| DC charge current limitation | 0x0391 | Yes/Yes | un32 = Charge current [0.1A], 0xFFFFFFFF = Not Available |
| DC discharge voltage | 0x0392 | Yes/Yes | un32 = Discharge voltage [0.01V] , 0xFFFFFFFF = Not Available |
| Battery discharge current limitation | 0x0393 | Yes/Yes | un32 = Discharge current [0.1A] , 0xFFFFFFFF = Not Available |
| Charger link percentage | 0x2014 | Yes/Yes | un8 = Percentage [1%], 0xFF = Not Available, valid range 0 till 100 |
| Charger link current limit | 0x2015 | Yes/Yes | un16 = Link Charge Current Limit [0.1A], 0xFFFF =Not Available |
| | | | |
| Settings | This VREG's can be read and written. | | |
| Synchronize group number | 0x0374 | No / Yes | Un8 = group, 0 = Disabled, 1-3 = Enabled. Used to synchronize multiple BMSS in parallel that are set to this group number. |

| Description | VREG ID | Period-ically/on Change | Comments |
|--|--------------------------------------|-------------------------|--|
| Battery strategy | 0x0376 | No / Yes | Un8 = Battery strategy, 0 = Default, 1 = Performance. |
| Combined BMS | 0x0377 | No / Yes | Un8 = Combined BMS, 0 = Disabled, 1 = Enabled. |
| Re-start request | 0x0379 | No / Yes | Un8 = Restart request, 0 = Disabled, 1 = Enabled, BMS will shut down and startup again. |
| Number of batteries in parallel | 0x0387 | No / Yes | Un8 = batteries parallel, 0 = automatically detected, 1-96 = Number of batteries connected to BMS in parallel. |
| Number of batteries in series | 0x0388 | No / Yes | Un8 = batteries series, 0 = automatically detected, 1-96 = Number of batteries connected to BMS in series. |
| Read 0xFF = Not available (System is in error state) | | | |
| | | | |
| Control | This VREG's can be read and written. | | |
| Combined control State | 0x0378 | No / Yes | Un8 = Combined BMS state: Un8 = address: // Combined BMS state: WAITING_FOR_USER = 0x00 PRECHARGING = 0x01 OPERATING = 0x02 RECEIVED_SWITCH_START_COMMAND = 0x10 RECEIVED_CANBUS_START_COMMAND = 0x11 When master BMS is transmitting a received start command, other master will go into interrupted state and for 5 seconds they will not accept any command. |
| Output Voltage | 0x037A | Yes/No | Un32 = Voltage [0.01V], 0xFFFFFFFF = Output not active. |

3.4.3 Examples

Request (0x0001) for Firmware Version (0x0102) of node at address 0x50 from address 0x20:

| CAN-ID | Data |
|------------|---|
| 0x1CEF5020 | 0x66 0x99 0x01 0x00 0x02 0x01 0xFF 0xFF |

Reply (is always broadcast) firmware version 1.04:

| CAN-ID | Data |
|------------|---|
| 0x1CEFFF50 | 0x66 0x99 0x02 0x01 0x00 0x00 0x04 0x01 |

If the request was not supported for this register, the reply will be an ACK (0x0002) with code 0x8000, invalid request:

| CAN-ID | Data |
|------------|---|
| 0x1CEF2050 | 0x66 0x99 0x02 0x00 0x02 0x01 0x00 0x80 |

3.5 MG energy systems REGS

3.5.1 Message definition

CAN-ID : 1CEF <target address><source address>

Example : 1CEF5030 means source address 0x30 end target address 0x50

0xFF as target address means broadcast message. Every node will receive this message.

All fields are sent in Little Endian order. Message data of a MGREG looks like the following:

Table 8 - MGREG message data

| Byte 0 | Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 | Byte 6 | Byte 7 |
|--------|--------|---------|---------|--------|--------|--------|--------|
| 0x88 | 0x9C | regId.L | regId.H | Data | Data | Data | Data |

3.5.2 MGREG ID List

| Description | MGREG ID | Period-ically/on Change | Comments |
|--------------------------|----------|-------------------------|--|
| System Voltage | 0x48EE | 250ms/No | Sn32 = Voltage [0.001V], 0x80000000 = Not Available. |
| System Status external 1 | 0x2140 | 250ms/Yes | un32 = Status 1 flags (bit flags) Bit 0 = Initializing, Bit 1 = Operational (ready to active DC-bus connection), Bit 2 = DC-bus connected, Bit 3 = Warning, Bit 4 = Failure, Bit 5 = Updating batteries, Bit 6 = Requested for system reset, Bit 7 = Input 1 state, Bit 8 = Input 2 state, Bit 9 = Input 3 state, Bit 10 = Programmable relay active, ... Bit 14 = Contactor close request by user, Bit 15 = Contactor is going to be opened, Bit 16 = DC-Bus Pre-Charging, Bit 17 = Charged, Bit 18 = Discharged, Bit 19 = Cell balancing, Bit 20 = Almost charged, Bit 21 = Almost discharged, Bit 22 = Charging allowed, Bit 23 = Discharging allowed , Bit 24 = Charging over temperature alert, Bit 25 = Discharging over temperature alert, Bit 26 = Charging under temperature alert, Bit 27 = Discharging under temperature alert, Bit 28 = battery power terminal over temperature alert, Bit 29 = battery contactor over temperature alert |

| Description | MGREG ID | Period-ically/on Change | Comments |
|---------------------------|----------|-------------------------|--|
| System Status external 2 | 0x2141 | 250ms/Yes | un32 = Status 2 flags (bit flags) Bit 0 = Combined standby, Bit 1 = Combined monitoring for equal battery-to-system voltage, Bit 2 = Service mode |
| System warning external 1 | 0x2142 | 5 sec./Yes | un32 = Warning 1 flags (bit flags) Bit 0 = Battery cell voltage too high, Bit 1 = Redundancy Unit battery voltage too high, Bit 2 = Battery cell voltage too low, Bit 3 = Redundancy Unit battery voltage too low, Bit 4 = Battery cell temperature too high for charging, Bit 5 = Battery cell temperature too high for discharging, Bit 6 = Redundancy Unit battery temperature too high, Bit 7 = Battery cell temperature too low for charging, Bit 8 = Battery cell temperature too low for discharging, Bit 9 = Redundancy Unit battery temperature too low, Bit 10 = Private CAN-bus communication timeout, Bit 11 = Public CAN-bus communication timeout, Bit 12 = Internal 12V power supply stability problem, Bit 13 = External 24V power supply stability problem, Bit 14 = Hardware failure, Bit 15 = Service request, Bit 16 = Battery terminal temperature too high, Bit 17 = Redundancy Unit minus terminal temperature too high, Bit 18 = Redundancy Unit plus terminal temperature too high, Bit 19 = Master internal temperature too high, Bit 20 ^a = Input 1, Bit 21 ^a = Input 2, Bit 22 ^a = Input 3, Bit 23 = Battery humidity high, Bit 24 = Private CAN-bus protocol violated, Bit 25 = Pre-charge fuse broken, Bit 26 = Fuse broken, Bit 27 = Battery contactor temperature too high. ^a) Only present when configured. |
| System warning external 2 | 0x2143 | 5 sec./Yes | un32 = Warning 2 flags (bit flags) Bit 0 = Battery cell voltages deviation detected, Bit 1 = Battery cell temperatures deviation detected, ... Bit 3 = Charge current too high, Bit 4 = Discharge current too high, Bit 5 = Battery leakage detected, Bit 6 = Master current overload. |

| Description | MGREG ID | Period-ically/on Change | Comments |
|---------------------------|----------|-------------------------|---|
| System failure external 1 | 0x2144 | 5 sec./Yes | <p>un32 = Failure 1 flags (bit flags)</p> <p>Bit 0 = Battery cell voltage too high, Bit 1 = Redundancy Unit battery voltage too high, Bit 2 = Battery cell voltage too low, Bit 3 = Second stage protection battery voltage too low, Bit 4 = Battery cell temperature too high for charging, Bit 5 = Battery cell temperature too high for discharging, Bit 6 = Second stage protection battery temperature too high, Bit 7 = Battery cell temperature too low for charging, Bit 8 = Battery cell temperature too low for discharging, Bit 9 = Redundancy Unit battery temperature too low, Bit 10 = Private CAN-bus communication timeout, Bit 11 = Public CAN-bus communication timeout, Bit 12 = Internal 12V power supply stability problem, Bit 13 = External 24V power supply stability problem, Bit 14 = Hardware failure, ... Bit 16 = Battery terminal temperature too high, Bit 17 = Redundancy Unit minus terminal temperature too high, Bit 18 = Redundancy Unit plus terminal temperature too high, Bit 19 = Battery redundancy unit interrupted the interlock, Bit 20 = Battery over current, Bit 21 = Battery contactor temperature too high.</p> |
| System failure external 2 | 0x2145 | 5 sec./Yes | <p>un32 = Failure 2 flags (bit flags)</p> <p>Bit 0 = Pre-Charging critical overload detected, Bit 1 = Pre-Charging took too long, Bit 2 = Contactor minus welding, Bit 3 = Contactor plus welding, Bit 4 = Contactor minus failure detected, Bit 5 = Contactor plus failure detected, Bit 6 = High voltage interlock circuits, Bit 7 = E-Stop shutdown, Bit 8 = Battery initializing, Bit 9 = Battery updating, Bit 10 = Current sensor failure, Bit 11 = Initialization.</p> |

4 SMA PROTOCOL

The SMA protocol will only support 48V systems based on the specifications of the Sunny Island 6.0H. Invalid value of a un16 is marked with 0xFFFF and a sn16 with 0x8000.

4.1 Interface definition

Speed : 500 kbps
ID : 11-bit CAN 2.0A

4.2 Message definition

| <i>BMS Limits</i> | | | | Dir | Interval | |
|-------------------|------|---------------------------------|--|------|----------|---------|
| CAN-ID 0x351 | | | | Tx | 500 ms | |
| Name | | | | Type | Res. | Length |
| Byte 0 | Low | Battery charge voltage | | un16 | 0,1V | 16 bits |
| Byte 1 | High | | | | | |
| Byte 2 | Low | DC Charge current limitation | | sn16 | 0,1A | 16 bits |
| Byte 3 | High | | | | | |
| Byte 4 | Low | DC Discharge current limitation | | sn16 | 0,1A | 16 bits |
| Byte 5 | High | | | | | |
| Byte 6 | Low | Battery discharge voltage | | un16 | 0,1V | 16 bits |
| Byte 7 | High | | | | | |

| <i>Battery status</i> | | | | Dir | Interval | |
|-----------------------|------|---------------------|--|------|----------|---------|
| CAN-ID 0x355 | | | | Tx | 500 ms | |
| Name | | | | Type | Res. | Length |
| Byte 0 | Low | SOC value | | un16 | 1% | 16 bits |
| Byte 1 | High | | | | | |
| Byte 2 | Low | SOH value | | un16 | 1% | 16 bits |
| Byte 3 | High | | | | | |
| Byte 4 | Low | SOC high resolution | | un16 | 0,01% | 16 bits |
| Byte 5 | High | | | | | |

| <i>Battery basic info</i> | | | | Dir | Interval | |
|---------------------------|------|-----------------|--|------|----------|---------|
| CAN-ID 0x356 | | | | Tx | 500 ms | |
| Name | | | | Type | Res. | Length |
| Byte 0 | Low | Battery voltage | | sn16 | 0,01V | 16 bits |
| Byte 1 | High | | | | | |
| Byte 2 | Low | Battery current | | sn16 | 0,1A | 16 bits |
| Byte 3 | High | | | | | |
| Byte 4 | Low | Temperature | | sn16 | 0,1°C | 16 bits |
| Byte 5 | High | | | | | |

| Alarm and warning information | | | | Dir | Interval | |
|-------------------------------|--------|-------|---|----------|------------------------------------|--------|
| | CAN-ID | 0x35A | | Tx | 500 ms | |
| | | | | | | |
| | Bit | Name | Type | Res. | Length | |
| Alarms | Byte 0 | 0 | General alarm | Bitfield | 1=Alarm raised, 2=Alarm cleared | 2 bits |
| | | 2 | Battery high voltage alarm | | | 2 bits |
| | | 4 | Battery low voltage alarm | | | 2 bits |
| | | 6 | Battery high temperature alarm | | | 2 bits |
| | Byte 1 | 0 | Battery low temperature alarm | | | 2 bits |
| | | 2 | Battery high temperature charge alarm | | | 2 bits |
| | | 4 | Battery low temperature charge alarm | | | 2 bits |
| | | 6 | Battery high current alarm | | | 2 bits |
| | Byte 2 | 0 | Battery high charge current alarm | | | 2 bits |
| | | 2 | Contactor alarm | | | 2 bits |
| | | 4 | Short circuit alarm | | | 2 bits |
| | | 6 | BMS internal alarm | | | 2 bits |
| | Byte 3 | 0 | Cell imbalance alarm | | | 2 bits |
| | | 2 | Reserved | | | 2 bits |
| | | 4 | Reserved | | | 2 bits |
| | | 6 | Reserved | | | 2 bits |
| Warnings | Byte 4 | 0 | General warning | Bitfield | 1=Warn. raised, 2=Warn. cleared | 2 bits |
| | | 2 | Battery high voltage warning | | | 2 bits |
| | | 4 | Battery low voltage warning | | | 2 bits |
| | | 6 | Battery high temperature warning | | | 2 bits |
| | Byte 5 | 0 | Battery low temperature warning | | | 2 bits |
| | | 2 | Battery high temperature charge warning | | | 2 bits |
| | | 4 | Battery low temperature charge warning | | | 2 bits |
| | | 6 | Battery high current warning | | | 2 bits |
| | Byte 6 | 0 | Battery high charge current warning | | | 2 bits |
| | | 2 | Contactor warning | | | 2 bits |
| | | 4 | Short circuit warning | | | 2 bits |
| | | 6 | BMS internal warning | | | 2 bits |
| | Byte 7 | 0 | Cell imbalance warning | | | 2 bits |
| | | 2 | Reserved | | | 2 bits |
| | | 4 | Reserved | | | 2 bits |
| | | 6 | Reserved | | | 2 bits |

| Event information | | | | Dir | Interval | |
|-------------------|--------|-------|---------------------------------------|----------|----------|--------|
| | CAN-ID | 0x35B | | Tx | 500 ms | |
| Events | Bit | | Name | Type | Res. | Length |
| | Byte 0 | 0 | Start of SOC Recalibration (not used) | Bitfield | 1=active | 1 bits |
| | | 1 | Stop of SOC Recalibration (not used) | | | 1 bits |
| | | 2 | Start of Power limitation (not used) | | | 1 bits |
| | | 3 | Stop of Power limitation (not used) | | | 1 bits |
| | | 4 | Preventive battery shutdown | | | 1 bits |
| | | 5 | reserved | | | 1 bits |
| | | 6 | reserved | | | 1 bits |
| | | 7 | reserved | | | 1 bits |

| Manufacturer name | | | | Dir | Interval | |
|-------------------|--------|-------|-----------------------------|------|----------|--------|
| | CAN-ID | 0x35E | | Tx | 500 ms | |
| | | | Name | Type | Res. | Length |
| | Byte 0 | | Manufacturer name: "MG-BMS" | Char | | |
| | Byte 1 | | | | | |
| | Byte 2 | | | | | |
| | Byte 3 | | | | | |
| | Byte 4 | | | | | |
| | Byte 5 | | | | | |
| | Byte 6 | | | | | |
| | Byte 7 | | | | | |

| System Information | | | | Dir | Interval | |
|--------------------|--------|-------|---|------|----------|---------|
| | CAN-ID | 0x35F | | Tx | 500 ms | |
| | | | Name | Type | Res. | Length |
| | Byte 0 | Low | Master type ID 0x3A9B -> 15003 | un16 | | 16 bits |
| | Byte 1 | High | | | | |
| | Byte 2 | High | Software version (note: MSB first) 0x0118 -> V1.24 | un16 | | 16 bits |
| | Byte 3 | Low | | | | |
| | Byte 4 | Low | Total battery capacity Ah | un16 | 1 Ah | 16 bits |
| | Byte 5 | High | | | | |
| | Byte 6 | Low | Master product ID hardware configuration. | un16 | | 16 bits |
| | Byte 7 | High | | | | |

5 GENERAL BMS PROTOCOL

The general BMS protocol will support 24 and 48V systems. Invalid value of a un16 is marked with 0xFFFF, sn16 with 0x8000 and a un32 with 0xFFFFFFFF.

5.1 Interface definition

Speed : 500 kbps
ID : 11-bit CAN 2.0A

5.2 Message definition

| <i>BMS Limits</i> | | | | Dir | Interval | |
|-------------------|------|---------------------------------|--|------|----------|---------|
| CAN-ID 0x351 | | | | Tx | 500 ms | |
| Name | | | | Type | Res. | Length |
| Byte 0 | Low | Battery charge voltage | | un16 | 0,1V | 16 bits |
| Byte 1 | High | | | | | |
| Byte 2 | Low | DC Charge current limitation | | sn16 | 0,1A | 16 bits |
| Byte 3 | High | | | | | |
| Byte 4 | Low | DC Discharge current limitation | | sn16 | 0,1A | 16 bits |
| Byte 5 | High | | | | | |
| Byte 6 | Low | Battery discharge voltage | | un16 | 0,1V | 16 bits |
| Byte 7 | High | | | | | |

| <i>Battery status</i> | | | | Dir | Interval | |
|-----------------------|------|---------------------|--|------|----------|---------|
| CAN-ID 0x355 | | | | Tx | 500 ms | |
| Name | | | | Type | Res. | Length |
| Byte 0 | Low | SOC value | | un16 | 1% | 16 bits |
| Byte 1 | High | | | | | |
| Byte 2 | Low | SOH value | | un16 | 1% | 16 bits |
| Byte 3 | High | | | | | |
| Byte 4 | Low | SOC high resolution | | un16 | 0,01% | 16 bits |
| Byte 5 | High | | | | | |

| <i>Battery basic info</i> | | | | Dir | Interval | |
|---------------------------|------|-----------------|--|------|----------|---------|
| CAN-ID 0x356 | | | | Tx | 500 ms | |
| Name | | | | Type | Res. | Length |
| Byte 0 | Low | Battery voltage | | sn16 | 0,01V | 16 bits |
| Byte 1 | High | | | | | |
| Byte 2 | Low | Battery current | | sn16 | 0,1A | 16 bits |
| Byte 3 | High | | | | | |
| Byte 4 | Low | Temperature | | sn16 | 0,1°C | 16 bits |
| Byte 5 | High | | | | | |

| Alarm and warning information | | | | Dir | Interval | |
|-------------------------------|--------|--------|---|----------|------------------------------------|--------|
| | | CAN-ID | 0x35A | Tx | 500 ms | |
| Name | | | | Type | Res. | Length |
| Alarms | Byte 0 | 0 | General alarm | Bitfield | 1=Alarm raised, 2=Alarm cleared | 2 bits |
| | | 2 | Battery high voltage alarm | | | 2 bits |
| | | 4 | Battery low voltage alarm | | | 2 bits |
| | | 6 | Battery high temperature alarm | | | 2 bits |
| | Byte 1 | 0 | Battery low temperature alarm | | | 2 bits |
| | | 2 | Battery high temperature charge alarm | | | 2 bits |
| | | 4 | Battery low temperature charge alarm | | | 2 bits |
| | | 6 | Battery high current alarm | | | 2 bits |
| | Byte 2 | 0 | Battery high charge current alarm | | | 2 bits |
| | | 2 | Contactor alarm | | | 2 bits |
| | | 4 | Short circuit alarm | | | 2 bits |
| | | 6 | BMS internal alarm | | | 2 bits |
| | Byte 3 | 0 | Cell imbalance alarm | | | 2 bits |
| | | 2 | Reserved | | | 2 bits |
| | | 4 | Reserved | | | 2 bits |
| | | 6 | Reserved | | | 2 bits |
| Warnings | Byte 4 | 0 | General warning | Bitfield | 1=Warn. raised, 2=Warn. cleared | 2 bits |
| | | 2 | Battery high voltage warning | | | 2 bits |
| | | 4 | Battery low voltage warning | | | 2 bits |
| | | 6 | Battery high temperature warning | | | 2 bits |
| | Byte 5 | 0 | Battery low temperature warning | | | 2 bits |
| | | 2 | Battery high temperature charge warning | | | 2 bits |
| | | 4 | Battery low temperature charge warning | | | 2 bits |
| | | 6 | Battery high current warning | | | 2 bits |
| | Byte 6 | 0 | Battery high charge current warning | | | 2 bits |
| | | 2 | Contactor warning | | | 2 bits |
| | | 4 | Short circuit warning | | | 2 bits |
| | | 6 | BMS internal warning | | | 2 bits |
| | Byte 7 | 0 | Cell imbalance warning | | | 2 bits |
| | | 2 | Reserved | | | 2 bits |
| | | 4 | Reserved | | | 2 bits |
| | | 6 | Reserved | | | 2 bits |

| Event information | | | Dir | Interval | |
|-------------------|--------|-------|---------------------------------------|----------|--------|
| | CAN-ID | 0x35B | Tx | 500 ms | |
| Events | Bit | Name | Type | Res. | Length |
| | Byte 0 | 0 | Start of SOC Recalibration (not used) | 1=active | 1 bits |
| | | 1 | Stop of SOC Recalibration (not used) | | 1 bits |
| | | 2 | Start of Power limitation (not used) | | 1 bits |
| | | 3 | Stop of Power limitation (not used) | | 1 bits |
| | | 4 | Preventive battery shutdown | | 1 bits |
| | | 5 | reserved | | 1 bits |
| | | 6 | reserved | | 1 bits |
| | | 7 | reserved | | 1 bits |

| Manufacturer name | | | Dir | Interval | |
|-------------------|--------|-------|-----------------------------|----------|--------|
| | CAN-ID | 0x35E | Tx | 500 ms | |
| | Name | | Type | Res. | Length |
| | Byte 0 | | Manufacturer name: "MG-BMS" | Char | |
| | Byte 1 | | | | |
| | Byte 2 | | | | |
| | Byte 3 | | | | |
| | Byte 4 | | | | |
| | Byte 5 | | | | |
| | Byte 6 | | | | |
| | Byte 7 | | | | |

| System Information | | | Dir | Interval | |
|--------------------|--------|-------|---|----------|---------|
| | CAN-ID | 0x35F | Tx | 500 ms | |
| | Name | | Type | Res. | Length |
| | Byte 0 | Low | Master type ID 0x3A9B -> 15003 | un16 | 16 bits |
| | Byte 1 | High | | | |
| | Byte 2 | High | Software version (note: MSB first) 0x0118 -> V1.24 | un16 | 16 bits |
| | Byte 3 | Low | | | |
| | Byte 4 | Low | Total battery capacity Ah | un16 | 16 bits |
| | Byte 5 | High | | | |
| | Byte 6 | Low | Master product ID hardware configuration. | un16 | 16 bits |
| | Byte 7 | High | | | |

| Battery cell info | | | | Dir | Interval | |
|-------------------|------|--------------------------|--|------|----------|---------|
| CAN-ID 0x373 | | | | Tx | 500 ms | |
| Name | | | | Type | Res. | Length |
| Byte 0 | Low | Lowest cell voltage | | un16 | 1mV | 16 bits |
| Byte 1 | High | | | | | |
| Byte 2 | Low | Highest cell voltage | | un16 | 1mV | 16 bits |
| Byte 3 | High | | | | | |
| Byte 4 | Low | Lowest cell temperature | | un16 | 1Kelvin | 16 bits |
| Byte 5 | High | | | | | |
| Byte 6 | Low | Highest cell temperature | | un16 | 1Kelvin | 16 bits |
| Byte 7 | High | | | | | |

| Energy charged and discharged | | | | Dir | Interval | |
|-------------------------------|------|-------------------|--|------|----------|---------|
| CAN-ID 0x378 | | | | Tx | 500 ms | |
| Name | | | | Type | Res. | Length |
| Byte 0 | Low | Energy charged | | un32 | 0,01KWh | 32 bits |
| Byte 1 | | | | | | |
| Byte 2 | | | | | | |
| Byte 3 | High | | | | | |
| Byte 4 | Low | Energy Discharged | | un32 | 0,01KWh | 32 bits |
| Byte 5 | | | | | | |
| Byte 6 | | | | | | |
| Byte 7 | High | | | | | |

| Serial number high part | | | | Dir | Interval | |
|-------------------------|--|--|--|------|----------|--------|
| CAN-ID 0x380 | | | | Tx | 500 ms | |
| Name | | | | Type | Res. | Length |
| Byte 0 | | BMS serial number, first 8 characters. | | Char | | |
| Byte 1 | | | | | | |
| Byte 2 | | | | | | |
| Byte 3 | | | | | | |
| Byte 4 | | | | | | |
| Byte 5 | | | | | | |
| Byte 6 | | | | | | |
| Byte 7 | | | | | | |

| Serial number low part | | | Dir | Interval | |
|------------------------|--------|---------------------------------------|------|----------|--------|
| | CAN-ID | 0x381 | Tx | 500 ms | |
| | | | | | |
| Name | | | Type | Res. | Length |
| Byte 0 | | BMS serial number, last 8 characters. | Char | | |
| Byte 1 | | | | | |
| Byte 2 | | | | | |
| Byte 3 | | | | | |
| Byte 4 | | | | | |
| Byte 5 | | | | | |
| Byte 6 | | | | | |
| Byte 7 | | | | | |